

# Frame-Based Representation of Lexical, Graphical, and Factual Knowledge for Text-to-Scene Generation

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## Text-to-Scene Generation

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# WordsEye

[Coyne and Sproat, 2001]

The screenshot shows the WordsEye Workspace web application. The browser address bar displays the URL <http://lucky.cs.columbia.edu:2001/workspace?scene-id=216>. The page header includes navigation links: **Workspace**, My Portfolio, Picturebook Editor, Forum, and Gallery. The main content area features a 3D scene titled "3D Scene - scene-216-render" showing a blue classic car with a person standing next to it. Text labels are overlaid on the scene: "I've come to trim the hedge" above the person and "I'm too young to die" above a small object on the ground. On the left side, there is a text input area with the prompt "Type a picture" and a paragraph of text: "a rodent is in front of a car, the rodent is facing right, the ground is pavement, death is right of the car, it is night, a large yellow illuminator is 5 feet above the car, the camera light is dark, 2 huge dice are in front of the death, they are 3 feet above the ground, a tiny 'I've come to trim the hedge' is above death. A tiny 'I'm too young to die' is above the rodent." Below this text is a "Display Scene" button and two checked options: "Keep same objects" and "Keep same view". At the bottom, there is a "Camera Controls" section with buttons for "New Scene", "Save Scene", "Undo", "Test Render", and "Final Render".

More eye-candy: <http://www.wordseye.com/>

# Levels of Scene Description

- ▶ **High-Level:**

- ▶ Functional view: Who does what to whom?
- ▶ **Wash**(washer: $x_1$ , theme: $x_2$ )
- ▶ Descriptions involves action/event verbs, complex entities...

- ▶ **Low-level:**

- ▶ Realization view: How is it done?  
(graphical: what does it look like)
- ▶ **On**(figure: $x_1$ , ground: $x_2$ ), **Grasp**(grasper: $x_1$ , theme: $x_3$ ),  
**Reach**(reacher:  $x_1$ , ground: $x_2$ ), **Kneel**(kneeler: $x_1$ )
- ▶ One high-level description → many low-level descriptions.

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# Translating from High-Level Descriptions to Low-level Graphical Representations

- ▶ Requires three sources of knowledge:
  - ▶ **Lexical Knowledge**
    - ▶ Textual description to high-level semantic representation.
  - ▶ **Graphical Knowledge**
    - ▶ Translate high-level semantics into low-level graphical relations.
  - ▶ **Factual Knowledge**
    - ▶ Guide translation, rule out impossible/unlikely graphical representations.
- ▶ Use a common frame-based representation to bridge between language, functional and graphical meaning.
- ▶ Starting point: Frame Semantics[Fillmore, 1982].



# Lexical Knowledge: Frame Semantics

[Fillmore, 1982]

- ▶ Word meaning can only be understood by referring to conceptual structure evoked by it.
- ▶ Frames are cognitive schemas describing relations between state/event participants.
- ▶ Semantic roles are specific to each frame (vs. universal roles or predicate-specific roles).
- ▶ Role of syntax and lexicon:
  - ▶ Valence patterns of a lexical item map syntactic arguments to frame elements.



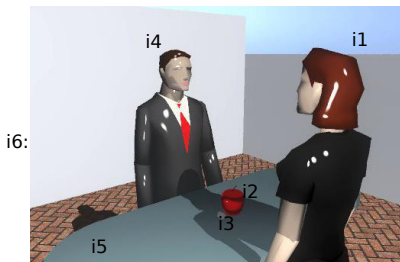
# Problem with FrameNet

[Mary]<sub>buyer</sub> **bought**<sub>Commerce\_buy</sub> [an apple]<sub>goods</sub> [for \$1]<sub>money</sub>.

- ▶ FrameNet annotations are 'shallow' (no semantic objects as arguments, just text spans).
- ▶ Cannot represent full sentence meaning
  - ▶ coreference, compositionality, . . . .
  - ▶ Want graph structure semantics.

# Instantiating Frames: Types and Instances

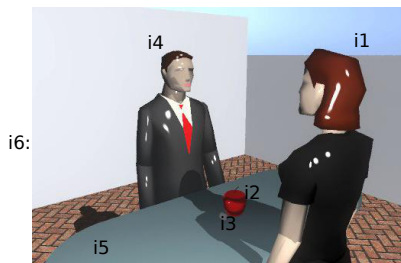
- ▶ Frames describe concept types.
- ▶ When lexical items evoke a frame in a description, the frame is instantiated.
- ▶ All frames carry a 'self' frame element, which is bound to the instance of the frame.
- ▶ When instantiating a frame, bind all the frame elements to instances (which may be defined by another frame).



**Commerce\_buy**(self: i6,  
buyer: i4,  
seller: i1,  
goods: i2,  
money: i3)

*'Mary bought an apple for \$1.'*

# Instantiating Frames: Sentence meaning as AVMs / DAGs



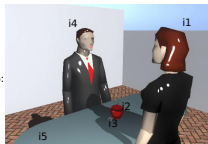
```
(i6 / Commerce_buy
  :buyer (i4 / Female
          :name "Mary")
  :seller (i5 / Human)
  :goods (i2 / Apple)
  :money (i3 / Money
          :currency "$"
          :value 1))
```



# Graphical Knowledge: Vignettes

[Coyne et al., 2011]

- ▶ Frames with decomposition, grounded in graphical primitives.
- ▶ Represent different realizations for lexical frames.
- ▶ Vignettes extend frames by
  - ▶ optionally introducing new frame elements that participate in the visualization.
  - ▶ decomposition into sub-frames:
    - ▶ link to specific 3D model types (frames describing entities).
    - ▶ describe graphical structure of a scene (frames describing events/situations).



**Commerce\_counter**( buyer, goods, money, seller)

**(ISA) Commerce\_buy**

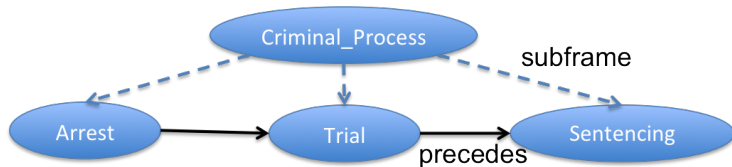
**at\_counter**(partcpt1:buyer, partcpt2:seller, counter:c)

**on**(figure:goods, ground:c)

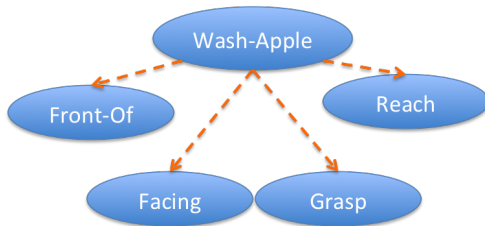
**on**(figure:money, ground:c)

# Graphical Knowledge: Vignette Decomposition

- ▶ (temporal) subframe relation in FrameNet:



- ▶ New frame-to-frame relation **subframe\_parallel**.





# Factual Knowledge

- ▶ Vignettes / Frames should define selectional restrictions on their frame elements to select the appropriate vignette.
- ▶ Some ontological information already incoded in frame-to-frame relations (ISA).
- ▶ In addition frame definitions for entity types need:
  - ▶ non-graphical properties of objects / attributes.
  - ▶ information about parts.
  - ▶ world knowledge ('apples grow on trees').

## Factual Knowledge

- ▶ Frame decompositions are declarative.
  - ▶ Simultaneously define properties of frame element fillers and restrict fillers to instances of frames that define this property.
- ▶ Can create frame elements for properties.
- ▶ Or use 'self' frame element to define properties of frames for entity types.

```
commerce_counter( buyer, goods, money, seller)
```

```
size(figure:goods, size:small)
```

```
animate(self:seller)
```

```
animate(self:buyer)
```

```
(ISA) commerce_buy
```

```
at_counter(partcpt1:buyer, partcpt2:seller, counter:c)
```

```
on(figure:goods, ground:c)
```

```
on(figure:money, ground:c)
```

```
apple( )
```

```
(ISA) fruit
```

```
size(figure:self, size:small)
```

```
shape(figure:self, shape:round)
```

# Status of the VigNet Resource

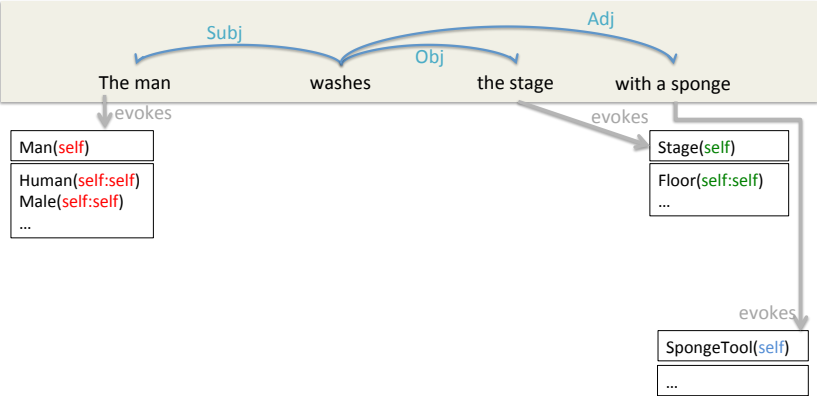
VigNet currently contains:

- ▶ a small set of primitive spatial relations (on, next-to (direction and distance), in, direction..)
- ▶ small set (about 30) 'abstract' vignettes
  - ▶ holding/touching target or patient, using handheld instruments, using stationary machine, human poses...
- ▶ several hundred verbal vignettes inheriting from and parametrizing abstract vignettes (ongoing...).
- ▶ about 2000 nominal vignettes mapping to about 3000 3D models (with physical attributes, parts, affordances).
- ▶ about 80 location vignettes (all rooms, including fixtures/affordances).

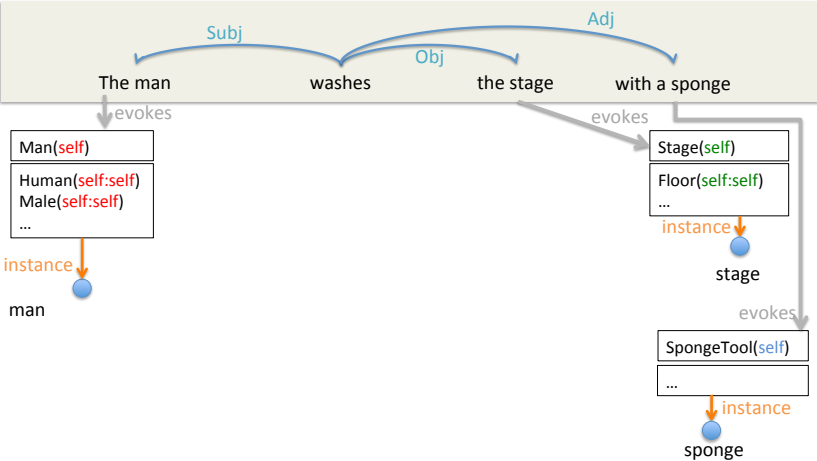
# Example Analysis



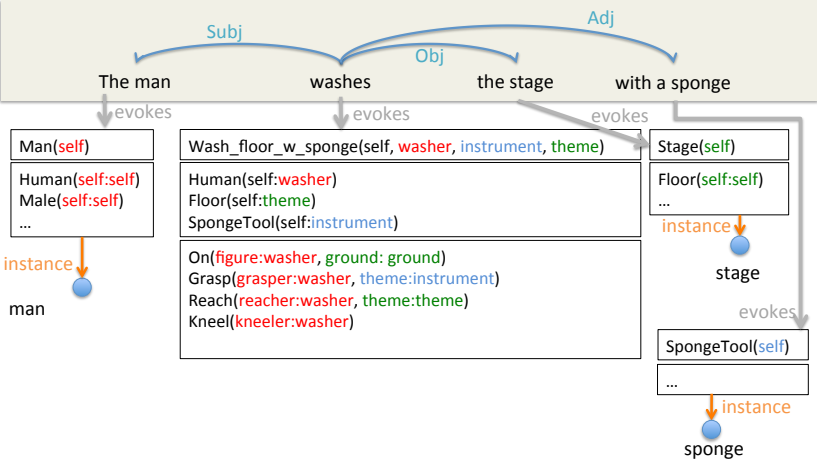
# Example Analysis



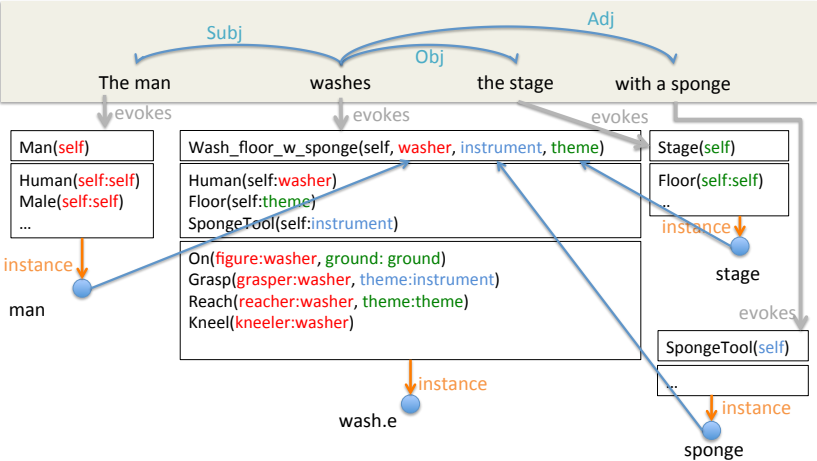
# Example Analysis



# Example Analysis

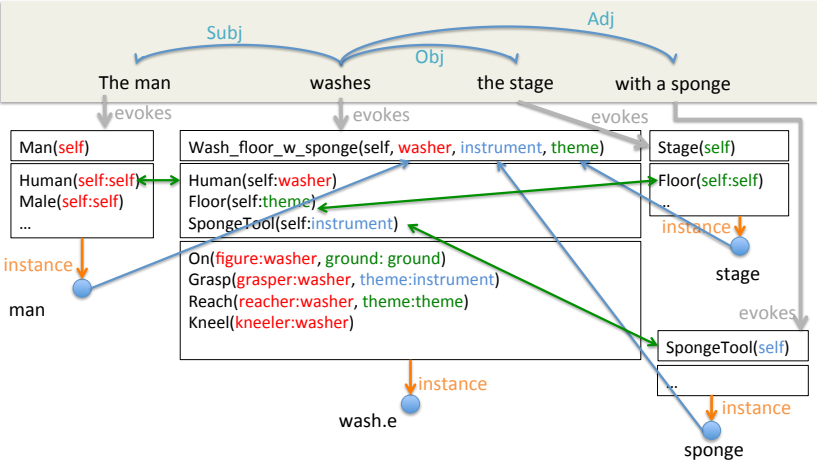


# Example Analysis



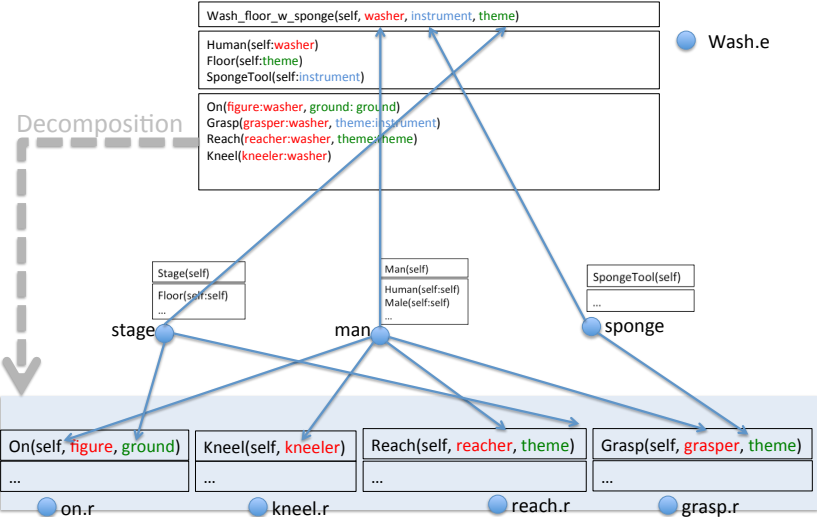


# Example Analysis



# Example Analysis

The man washes the stage with a sponge



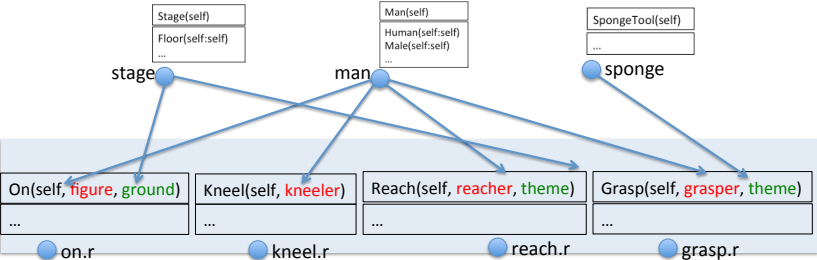
# Example Analysis

The man

washes

the stage

with a sponge



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### Inference in Text-to-Scene Generation

# Inference in Text-to-Scene Generation

Two levels of inference:

- ▶ Interpret primitive spatial relations (On, Near...) using spatial reasoning to create an actual 3D scene.
  - ▶ Already supported in WordsEye.
  - ▶ Currently adding support for more elaborate reasoning (in rooms etc, ...)
- ▶ Resolve high-level frame semantics into vignettes (**this talk**)
  - ▶ Two step approach:
    1. Parse into high-level functional frame semantics.
    2. Resolve to low-level vignettes.

# Semantic Parsing

- ▶ n-best dependency analysis for input sentence.
- ▶ create n-best FrameNet-style semantic parses for each frame evoking element and its frame elements in isolation:
  - ▶ Map input parse to previously observed frame annotations using statistical alignment model between syntactic dependency structures in FrameNet annotations and input.
  - ▶ Rank annotation hypotheses using semantic information.
- ▶ Construct forest of possible analyses for the entire sentence.

# Decoding the Hypothesis Forest / Finding Vignettes

- ▶ Find all possible vignettes for analyzed frames, find consistent sets of vignettes.
- ▶ Checking if a vignette assignment is consistent is easy:
  - ▶ Subsumption is easy: there is no negation or quantification.
  - ▶ Just check if selectional restrictions are met.
- ▶ Finding a consistent vignette annotation is hard:
  - ▶ Too many vignettes to check.
  - ▶ Methods from constraint solving?

# Greedy Vignette Annotation

- ▶ Greedy heuristics:
  - ▶ Moving down the parse tree, assign the most restrictive vignette first.
  - ▶ This limits the choice of other vignettes.
  - ▶ Could produce to more interesting realizations.
- ▶ Disadvantages:
  - ▶ May not be the right strategy, can miss solutions.
  - ▶ Not sure if syntactic structure should guide semantic composition.







# Thank you!



'the world is ROUND', by Gary Zamchick:

*the humongous white shiny bear is on the american mountain range. the mountain range is 100 feet tall. the ground is water. the sky is partly cloudy. the airplane is 90 feet in front of the nose of the bear. the airplane is facing right.*

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