Frames - Structures, Types, and Constraints

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Introduction

- Frames allow for a fine-grained representation of meaning, not only at the lexical level.
- Frames allow to capture generalizations via types.
- Integrating logical operators into frames allows us to combine these advantages with standard approaches to logical form.
- We can use a logic in order to formulate constraints on frames.
- We can use standard underspecification techniques on this logic in order to abstract over several readings.

The claim this talk wants to make is the following:

The combination of a) frame semantics with its system of types, b) a constraint language for frames that includes quantification, and c) underspecification of the constraints allows us to capture semantic generalizations in an elegant way.

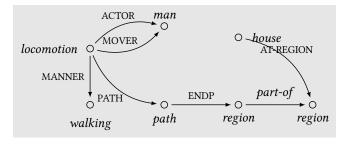
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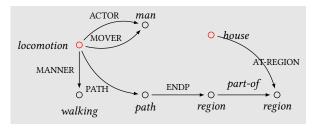
- Frames are a representation format of conceptual and lexical knowledge.
- They are commonly presented as semantic graphs with labelled nodes and edges where nodes correspond to entities (individuals, events, ...) and edges to (functional or non-functional) relations between these entities.



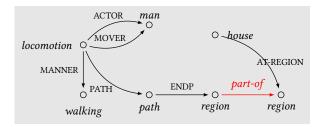
There are different ways in which the CRC projects focus on frames. However, there is a consensus of what type of structures and representations we mean when using the term *frame*.

Düsseldorf frames can be formalized as an extended form of typed features structures (Petersen, 2007; Kallmeyer & Osswald, 2013; Petersen & Osswald, 2014). They differ from standard feature structures in some aspects:

a) There need not be a unique root node, i. e., a single node from which all other nodes are reachable via attribute-value paths.

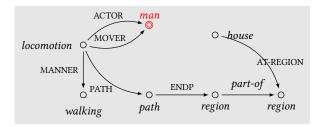


b) We can have relations between nodes, not only functional attributes.



(see also the comparators in Löbner, 2015)

c) We can focus on internal nodes of a frame, i. e., the frame is not only accessible via its source nodes.¹

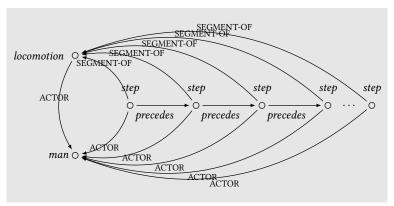


"the/a man who walked to the house"

¹Source node = node without an incoming edge.

Beyond this, the projects differ in the way they use frames.

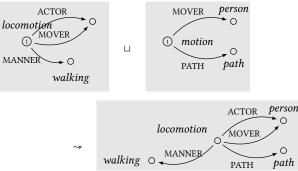
1. **Form of the frames**: What is a node in a frame and what is an attribute? What is implicitely given by a certain type and what do I spell out in the frame structure?– Different possibilities depending on the perspective one has on something.



2. Operations on frames: Unification is an important means for us

to combine frames.

a) identifications of root nodes:

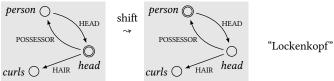


b) identifications of other nodes:

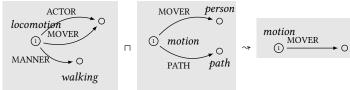


Other operations that play a role in the CRC:





Overlap/generalization:



and *zooming*.

Question: How can we integrate quantification and negation into frames?

This is important not only for standard quantifier examples such as

(1) every man loves a woman

but also for cases where quantification and event semantics interact in interesting ways. Here, we can combine the strengths of frame semantics with an approach to logical form.

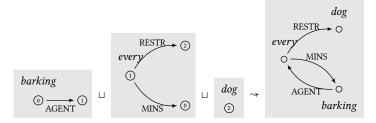
Rest of the talk:

- 1. Overview: Different strategies for integrating logical operators into frames.
- 2. One proposal: Combining hybrid logic and frame semantics.
- 3. Case study: progression and iteration in event semantics; the case of *for*-adverbials.

One possibility is to **include the logical operators into the frame structure**.

(2) every dog barked

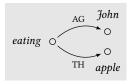
Frames according to Kallmeyer & Richter (2014):



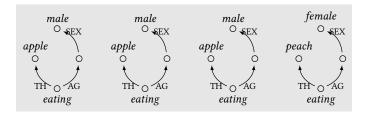
- Requires an additional mechanism to read off truth conditions from frames.
- Mixes aspects of meaning with aspects of logical form syntax.

Other possibility: **Separate logical operators from frames by using a logic to talk about frames**. This logic allows for negation and quantification.

Approach pursued by Muskens (2013).



- (3) a. John ate an apple
 - b. eating $e \circ AG e x \circ John x \circ TH e y \circ apple y$



(4) a. every man ate an apple
b. ∀x[∃z[person x ∘ SEX x z ∘ male z]w₀ → ∃ye[apple y ∘ eating e ∘ AG e x ∘ TH e y]w₀]
(wide scope of universal)

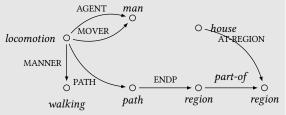
Kallmeyer et al. (2015a,b) follows Muskens (2013) by keeping frames (= our models) and logical operators (= part of the logic) separate.

Question: Which logic to choose in order to talk about frames?

Our proposal: extended version of modal logic (Blackburn et al., 2007)

- Modal logic has been proposed as a logic for feature structures (Blackburn, 1993).
- It supports the local perspective on graphs that we adopt when talking about frames: Formulas are evaluated in a specific node.
- Extensions of modal logic allow to incorporate the logical operators we need. This leads to *hybrid logic* (HL, Areces & ten Cate, 2007)

Hybrid logic for frames Model \mathcal{M}_1 :



- *region* is true in the two nodes on the right at the bottom.
- (AGENT) *man* is true at the *locomotion* node.
- *locomotion* ∧ (MANNER) *walking* ∧ (PATH)(ENDP) ⊤ is also true at the *locomotion* node.

HL extends this with

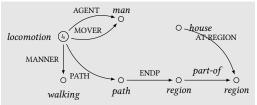
- the possibility to name nodes in order to go back to them without following a specific path;
- quantification over nodes.

Given:

- Rel = Func ∪ PropRel (functional/non-functionsl relational symbols),
- Type (type symbols = propositional variables),
- Nom (nominals = node names), Nvar (node variables), Node := Nom ∪ Nvar.

Forms ::= $\top |p| n |\langle R \rangle \phi | \exists \phi | @_n \phi | \downarrow x.\phi | \exists x.\phi | \neg \phi | \phi_1 \land \phi_2$

with $p \in \text{Type}$, $n \in \text{Node}$, $R \in \text{Rel}$, ϕ , ϕ_1 , $\phi_2 \in \text{Forms}$.

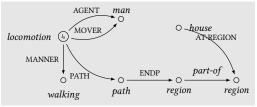


The truth of a formula is given with respect to a specific node w of a model \mathcal{M} and some assignment mapping Node to the nodes in \mathcal{M} . (For Nvar, this is g.)

J ϕ is true in *w* if there exists a *w'* in \mathcal{M} that makes ϕ true. (I.e., we move into some node in our frame and there ϕ is true.) **J***house* is true in any node in \mathcal{M}_1 .

As usual: $\forall \phi \equiv \neg \exists (\neg \phi)$ $\forall (path \rightarrow \langle ENDP \rangle \top)$ is true in any node in \mathcal{M}_1 .

Q_nφ is true in w if φ is true in the node assigned to n.
 (We move into the (unique) node named n and there, φ holds.)
 Q_b locomotion is true in any node in M₁.



↓ *x*. φ is true in *w* if φ is true in *w* under the assignment g^x_w.
 (We call the node we are located at *x*, and then φ is true in that node.)

 $\langle PATH \rangle \langle ENDP \rangle \langle part-of \rangle \downarrow x.(region \land \exists (house \land \langle AT-REGION \rangle x))$ is true in the *locomotion* node in \mathcal{M}_1 .

∃*x*.φ is true in *w* if there is a *w*′ such that φ is true in *w* under an assignment *g*^{*x*}_{*w*}.
 (There is a node that we name *x* but for the evaluation of φ, we do not move to that node.)
 ∃*x*.⟨PATH⟩⟨ENDP⟩⟨*part-of*⟩(*x*∧*region*)∧∃(*house*∧⟨AT-REGION⟩*x*)

is true in the *locomotion* node in \mathcal{M}_1 .

Idea:

- Pair each syntactic building block with a set of underspecified HL formulas, which can contain holes and which can be labeled.
- Composition is then triggered by unifications of interface features that arise from syntactic composition.

In the following, $\{0, 1, 2, ...\}$ are HL nominals while $\{[0, 1, 2, ...\}$ are variables at the interface.

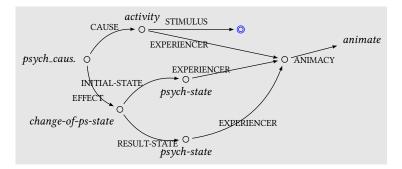
Example from C08: *psych* verbs and *-ment* nominalization: Syntactic rule (*ment* construction):

 $[X_{[CAT=V, SEM=0]} - ment]_{[CAT=N, SEM=1]}$

Semantic constraints paired with this:

```
\exists x.@_{0} [psych_causation \\ \land (CAUSE) [activity \\ \land (STIMULUS) \top \\ \land (EXPERIENCER) [x \land (ANIMACY) animate]] \\ \land (EFFECT) [change-of-psych-state \\ \land (INITIAL-STATE) [psych-state \\ \land (EXPERIENCER) x] \\ \land (RESULT-STATE) [psych-state \\ \land (EXPERIENCER) x] ] \\ \land [(CAUSE) 1 \lor (CAUSE) (STIMULUS) 1 \\ \lor (EFFECT) 1 \lor (EFFECT) (RESULT-STATE) 1]]
```

There are several minimal models (= models whose nodes are all described in the formula) for the resulting semantics of a *ment*-construction.



etc.

Such a computation of a minimal model can be done by XMG (Lichte & Petitjean, 2015).

We can separate constraints on the form of psych verbs from the *ment*-construction:

General constraints:

- (5) a. $\forall psych_causation \rightarrow causation$
 - b. $\forall causation \rightarrow \langle CAUSE \rangle \top \land \langle EFFECT \rangle \top$
 - c. $\forall psych_causation \rightarrow [\langle CAUSE \rangle \langle STIMULUS \rangle \top \land \langle CAUSE \rangle \langle EXPERIENCER \rangle \top]$
 - d. $\forall psych_causation \rightarrow \exists x.[\langle CAUSE \rangle \langle EXPERIENCER \rangle x \land \langle EFFECT \rangle \langle EXPERIENCER \rangle x]$ e. ...

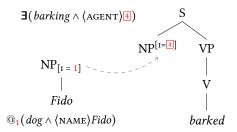
ment-construction:

(6) a.
$$[X_{[CAT=V, SEM=0]} - ment]_{[CAT=N, SEM=1]}$$

b. $@_{0}[psych_causation \land [(CAUSE)1 \lor (CAUSE)(STIMULUS)1 \lor (EFFECT)1 \lor (EFFECT)(RESULT-STATE)1]]$

A simple example from A02:

(7) Fido barked.



Putting things together (=conjoining) yields

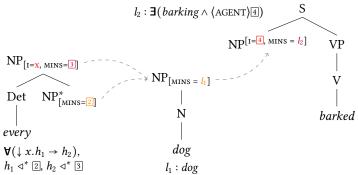
(8) $\exists (barking \land (AGENT)1) \land @_1(dog \land (NAME)Fido)$

Adding underspecification: We can apply *hole semantics* (Bos, 1995) to our logic:

- We remove subformulas and replace them with *holes* (we "unplug" them).
- We introduce *dominance constraints* that tell us that a specific formula must be somewhere under a hole, i.e., must be a subformula of the formula that this hole stands for.
- We give names (= *labels*) to formulas in order to describe the way they are involved in dominance constraints.
- (9) a. every dog barked
 - b. $\forall (\downarrow x. dog \rightarrow \exists (barking \land (AGENT)x))$
 - c. $\forall (\downarrow x.h_1 \rightarrow h_2), l_1 : dog, l_2 : \exists (barking \land \langle AGENT \rangle x), h_1 \triangleleft^* l_1, h_2 \triangleleft^* l_2$

This is interesting because it allows us to capture several readings in one underspecified representation.

TAG derivation for (9-a):



(10)
$$\forall (\downarrow x.h_1 \rightarrow h_2), l_1 : dog, l_2 : \exists (barking \land \langle AGENT \rangle x), h_1 \triangleleft^* l_1, h_2 \triangleleft^* l_2$$

Disambiguation: $\forall (\downarrow x. dog \rightarrow \exists (barking \land \langle AGENT \rangle x))$

Atelicity and telicity and for-adverbials

- (11) Peter swam for one hour
- (12) Peter knocked at the door for ten minutes
 - In (11), the verb denotes an activity and is thus immediately compatible with the *for*-adverbial.
 - In (12), the verb denotes a punctual event, and, hence, calls for additional adjustments in order to be compatible with *for*adverbials.
- \Rightarrow (12) is interpreted as describing a sequence or iteration of knockings.

Atelicity and telicity and for-adverbials

Semantics of *for*-adverbials following Champollion (2013):

(13)
$$\lambda P \lambda I [AT(P, I) \land hours(I) = 1 \land \forall \mathcal{J} [\mathcal{J} \in \mathcal{R}_{I}^{short(I)} \to AT(P, \mathcal{J})]]$$

In other words, a *for*-adverbial can only apply to an event P if we can fix a partition of the entire time interval I such that in each of the smaller intervals \mathcal{J} , P holds as well.

- *swim* can be directly used as *P*.
- In the case of *knock*, one has to apply an iteration operator first (* *knock*), and the result can then become the argument of (13).

Goal of Kallmeyer et al. (2015b): provide an analysis with a similar semantics for *for*-adverbials that avoids the assumption of an iteration operator.

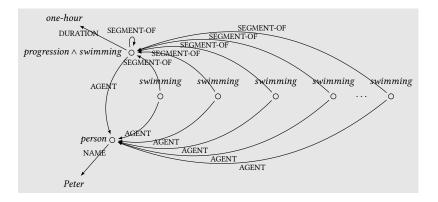
Atelicity and telicity and for-adverbials

Why frames? And why HL and underspecification?

- Frames and HL allow for a fine-grained event decomposition and for quantification over subevents.
- Underspecification in the logical formulas (= dominance constraints) allows to distinguish between embedded subevents and the entire event and to "leave some room" for adverbials to apply.
- Underspecification in the frame types, in combination with appropriate HL constraints on frames, allows us to underspecify the type of the event resulting from applying a *for*-adverbial while making this type dependent on the type of the embedded event.

(11) Peter swam for one hour

Representation in the frame:



(14) Peter + swam $@_i(person \land \langle NAME \rangle Peter) \land \exists swimming \land \langle AGENT \rangle i$

Idea:

- We want the **∃** to scope over the entire progression.
- Such a progression can be conceived as a sequence of smaller events of the same type.
- The *swimming* \land (AGENT)*i* describes these smaller events.
- Since the event is a progression, a general constraint will take care of lifting the *swimming* type to the entire event.

We therefore unplug the *swimming*... formula. Semantics of *swam*:

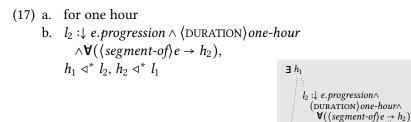
(15) $\exists h_1, l_1 : swimming \land \langle \text{Agent} \rangle i, h_1 \lhd^* l_1$

After combination with Peter and disambiguation, we obtain (14).

(11) Peter swam for one hour For *Peter swam*, we have

(16) $@_i(person \land \langle NAME \rangle Peter) \land$ $\exists h_1, l_1 : swimming \land \langle AGENT \rangle i, h_1 \triangleleft^* l_1$

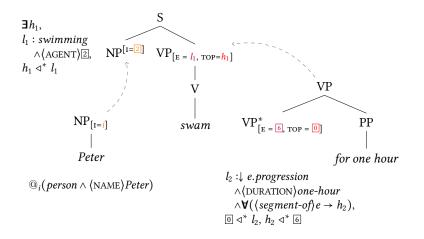
This combines (conjoins) with the semantics of for one hour:



 l_1 swimming $\land \langle AGENT \rangle i$

Syntax-semantics interface with TAG:

(11) Peter swam for one hour



This yields the underspecified representation:

(18) $@_i(person \land (NAME)Peter),$ $\exists h_1, l_2 :\downarrow e.progression \land (DURATION) one-hour \land \forall ((segment-of)e \rightarrow h_2),$ $l_1 : swimming \land (AGENT)i,$ $h_1 \lhd^* l_1, h_1 \lhd^* l_2, h_2 \lhd^* l_1$

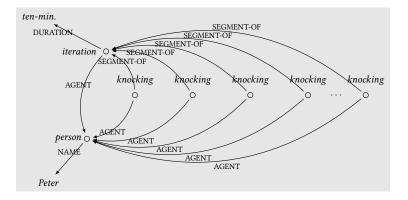
After disambiguation, one obtains:

Additional constraint lifting *P* to the entire event:

(20) $\forall (\downarrow e.progression \rightarrow \langle segment-of \rangle e)$

(12) Peter knocked at the door for ten minutes

Representation in the frame:



(12) Peter knocked at the door for ten minutes

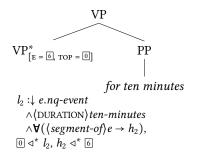
We adopt a more general type *nq-event* which is a supertype of *progression* and *iteration* and which is intended to capture *non-quantized* event types in the sense of Krifka (1998).

(21) \forall (nq-event \leftrightarrow iteration \lor progression) \forall (iteration $\rightarrow \neg$ progression)

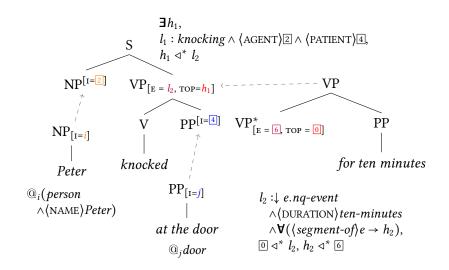
Additional constraints on iterations and progressions concerning the possible types of their segments:

(22) $\forall (\langle segment-of \rangle iteration \rightarrow bounded)$ $\forall (punctual \rightarrow bounded)$ $\forall (\langle segment-of \rangle progression \rightarrow \neg bounded)$

We generalize the lexical entry for *for*-adverbials:



Depending on the type of the event segments, the non-quantized event is either a progression or an iteration.



Result:

(23)
$$\exists h_1$$
,
 $l_1 : knocking \land \langle AGENT \rangle i \land \langle PATIENT \rangle j$,
 $l_2 :\downarrow e.nq-event \land \langle DURATION \rangle ten-minutes \land \forall (\langle segment-of \rangle e \rightarrow h_2)$,
 $@_i(person \land \langle NAME \rangle Peter)$,
 $@_jdoor$,
 $h_1 \lhd^* l_1, h_1 \lhd^* l_2, h_2 \lhd^* l_1$

After disambiguation:

(24)
$$\exists (\downarrow e.nq-event \land (\text{DURATION}) ten-minutes} \land \forall ((segment-of) e \rightarrow knocking \land (\text{AGENT}) i \land (\text{PATIENT}) j)) \land @_i(person \land (\text{NAME}) Peter) \land @_j door$$

With our constraints and with \forall (*knocking* \rightarrow *punctual*), *e* in (24) is necessarily of type *iteration*.

Conclusion

- Frames allow for a fine-grained representation of meaning where generalizations can be captured via types and constraints on types.
- We can use a logic in order to formulate constraints on frames and in order to integrate logical operators.
- We can use standard underspecification techniques on this logic in order to abstract over several readings.

We have seen that this combination allows us to capture semantic generalizations in an elegant way.

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