Syntax-Driven Semantic Composition: Constructional versus Lexical Meaning

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Overview

- 1. Motivation: Constructions contribute to meaning
- 2. Modelling constructions with Lexicalized Tree Adjoining Grammars
- 3. Semantic (de)composition: Directed motion expressions
- 4. Semantic (de)composition: Dative alternation

[Kallmeyer and Osswald, 2012b, Kallmeyer and Osswald, 2012a]

Motivation (1)

- The meaning of a verb-based construction does not only depend on the lexical meaning of the verb but also on its specific syntagmatic environment.
- This has led Construction Grammar to treating every linguistic expression as a construction [Goldberg, 1995].
- The influence of the syntagmatic context on the constitution of verb meaning has also been taken into account by lexicalist approaches to argument realization [Van Valin and LaPolla, 1997].

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Question: How are the meaning components distributed over the lexical and morphosyntactic units of a linguistic expression and how do these components combine?

Motivation (2): Dative alternation

Verbs like *give*, *send*, and *throw* can occur in both the double object (DO) and the prepositional object (PO) construction:

- (1) a. John sent Mary the book. (DO)
 - b. John sent the book to Mary. (PO)

Motivation (2): Dative alternation

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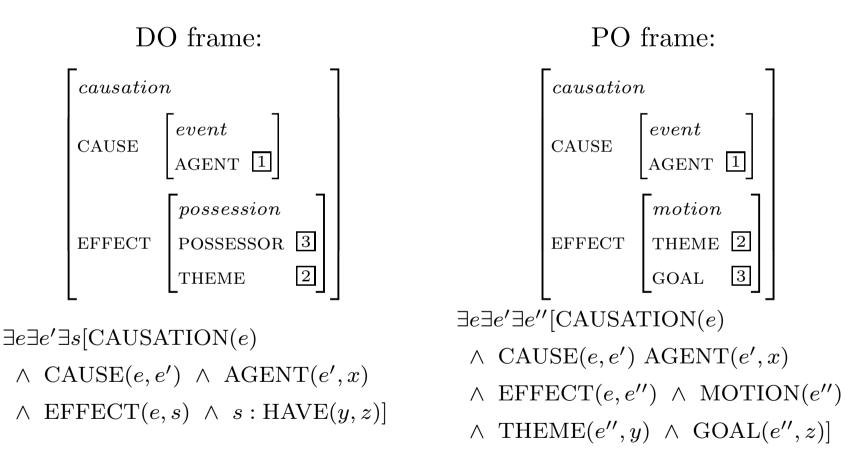
- (1) a. John sent Mary the book. (DO)
 - b. John sent the book to Mary. (PO)

These constructions are traditionally associated with a 'caused possession' (1-a) and 'caused motion' (1-b) interpretation, respectively [Goldberg, 1995].

(2) a. $\exists e \exists e' \exists s [CAUSATION(e) \land CAUSE(e, e') \land AGENT(e', x) \land EFFECT(e, s) \land s : HAVE(y, z)]$ (DO) b. $\exists e \exists e' \exists e'' [CAUSATION(e) \land CAUSE(e, e') AGENT(e', x) \land EFFECT(e, e'') \land MOTION(e'') \land THEME(e'', y) \land GOAL(e'', z)](PO)$

Motivation (3): Dative alternation

Representation as frames:



Motivation (4): Directed motion

Directional expressions in English can be constructed from verbs of motion and directional PPs. The relevant constructions include intransitive verbs of motion (3) as well as transitive verbs of caused motion and transport (4).

- (3) a. Mary walked to the house.
 - b. The ball rolled into the goal.
- (4) a. John threw/kicked the ball into the goal.
 - b. John pushed/pulled the cart to the station.
 - c. John rolled the ball into the hole.

Motivation (5): Directed motion

The motion verb does not lexicalize a *goal*.

- (5) a. Mary ran.
 - b. Mary ran to the house.
- (6) a. $\exists e[MOVE(e) \land AGENT(e, x)] \pmod{1}$
 - b. $\exists e[MOVE(e) \land AGENT(e, x) \land GOAL(e, y)]$

(directed motion)

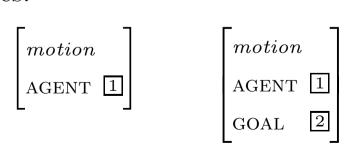
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Corresponding frames:



Motivation (6)

Question: How can we characterize the relevant constructions?

- DO construction: a verb having a subject NP, a dative NP and a direct object NP
- PO construction: a verb having a subject NP, a direct object NP and a *to*-PP
- Directed motion: a verb with a subject NP and a directional PP

Motivation (7)

Constructions can be discontinuous in a sentence. I.e., in the syntactic tree, they can cover different tree fragments that are not connected.

- (7) a. Whom does Mary want John to send the letter?
 - b. John sends his letters always to Mary.
 - c. He ran every day to the river.
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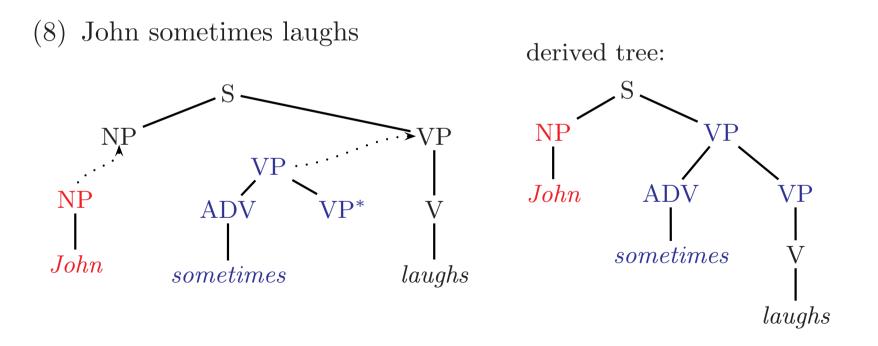
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- Our proposal: Lexicalized Tree Adjoining Grammars.

Tree Adjoining Grammars (TAG) [Joshi/Schabes 1997]: Tree-rewriting system: set of *elementary* trees with two operations: Adjunction: replacing an internal node with a new tree.

Substitution: replacing a leaf with a new tree.

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Adjunction: replacing an internal node with a new tree. Substitution: replacing a leaf with a new tree.



Important features of LTAG:

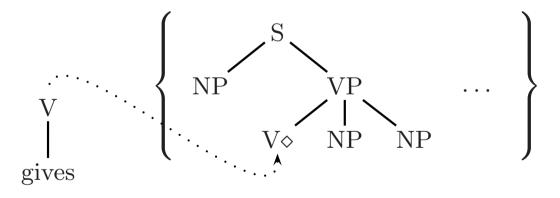
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- Recursive parts are put into separate elementary trees that can be adjoined (Factoring of recursion, FR)
- Elementary trees can be arbitrarily large, in particular (because of FR) they can contain elements that are far apart in the final derived tree (Extended domain of locality)
- The elementary tree of a lexical predicate contains slots (non-terminal leaves) for all arguments of the predicate, for nothing more.

- In a TAG, the trees are organized in tree families.
 Tree families group together trees belonging to the same subcategorization frame.
- The lexicon is further split into unanchored tree families and separate lexical anchors selecting for the tree families.

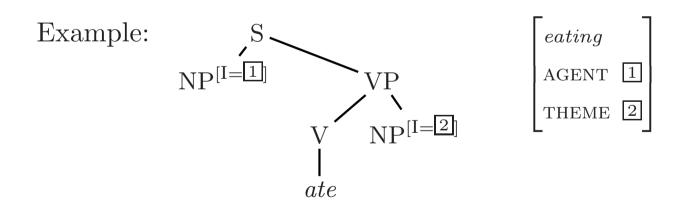


There are several reasons why LTAG seems a good candidate for a construction-based semantics:

• LTAG's extended domain of locality allows to acces all the syntactic slots that correspond to the semantic roles specified within the frame of a predicate since they are part of the same elementary tree.

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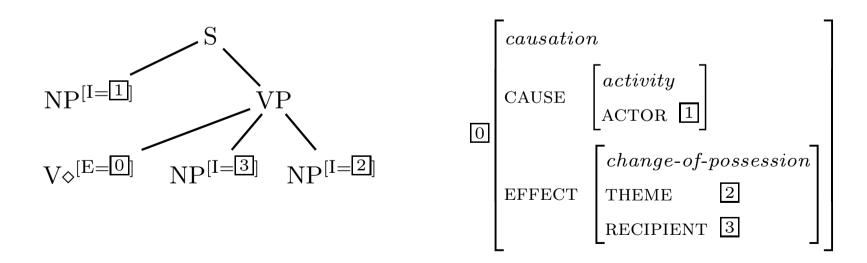
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Example: DO construction \approx caused change of possession

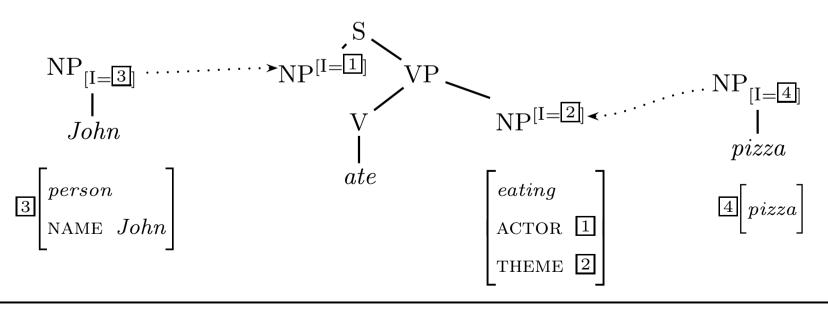


We assume a syntax-semantics interface where

- each elementary tree is linked to a semantic frame,
- semantic frames are typed feature structures with additional relations between their nodes, and
- semantic composition consists of unifications triggered by substitution and adjunction

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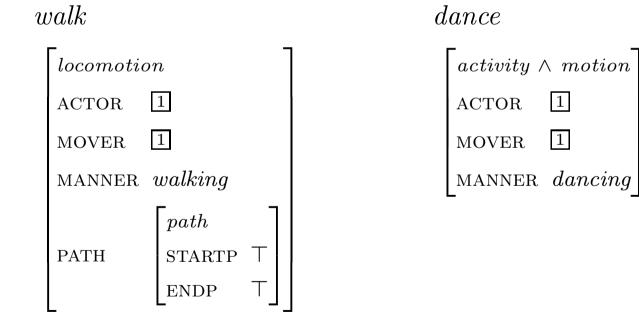
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Semantic (de)composition: Directed Motion (1)

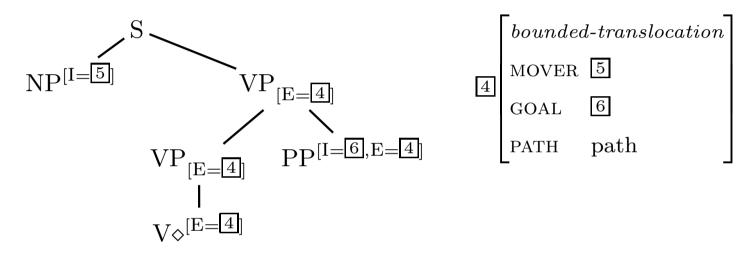
- (9) a. John walked into the house.
 - b. Mary danced into the room.

Lexical semantics of *walk* and *dance*:



Semantic (de)composition: Directed Motion (2)

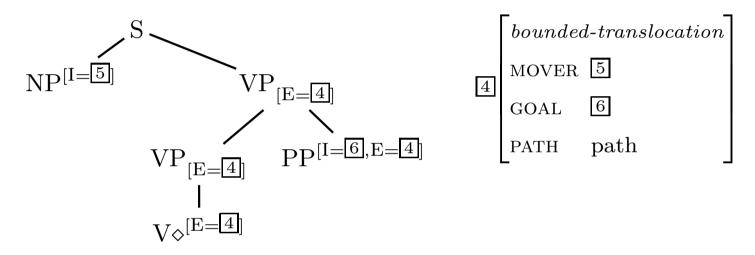
Directed motion construction:



The PP argument introduces a GOAL.

Semantic (de)composition: Directed Motion (2)

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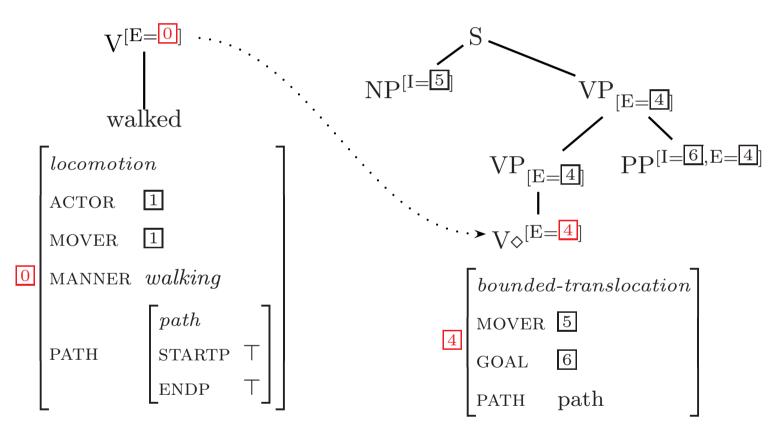
The PP argument introduces a GOAL.

Such a tree can be used for

(10) a. Mary walked/danced into the room.b. The ball rolled into the goal.

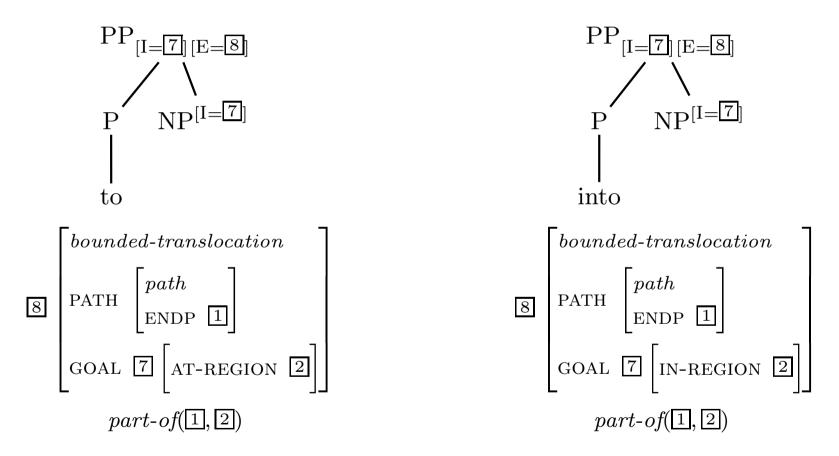
Semantic (de)composition: Directed Motion (3)

Lexical anchoring:



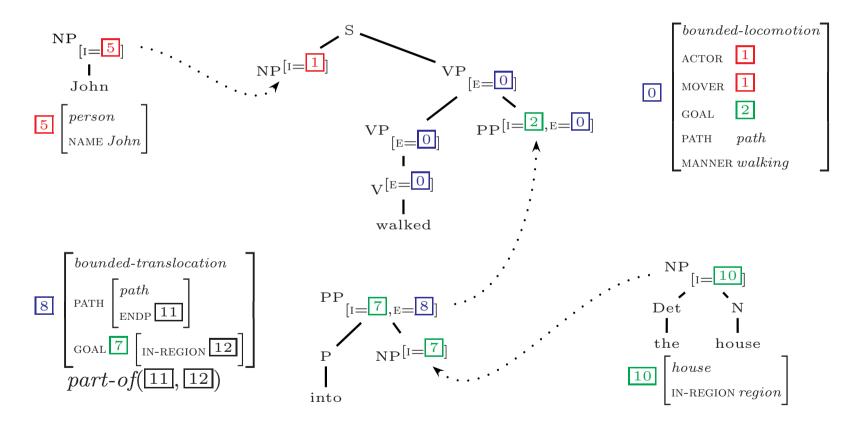
Semantic (de)composition: Directed Motion (4)

Elementary trees for some directional prepositions:



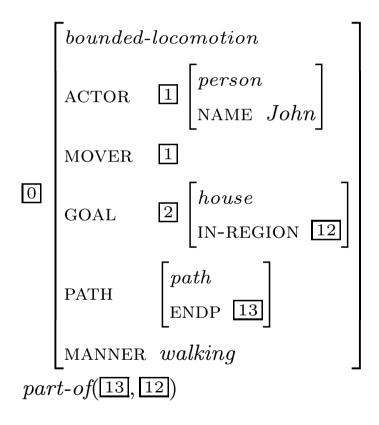
Semantic (de)composition: Directed Motion (5)

(11) John walked into the house



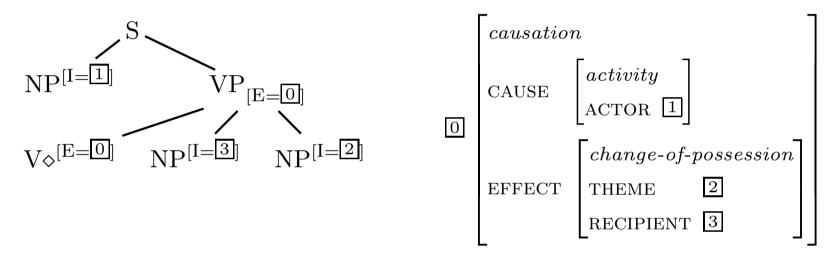
Semantic (de)composition: Directed Motion (6)

Resulting frame for John walked into the house



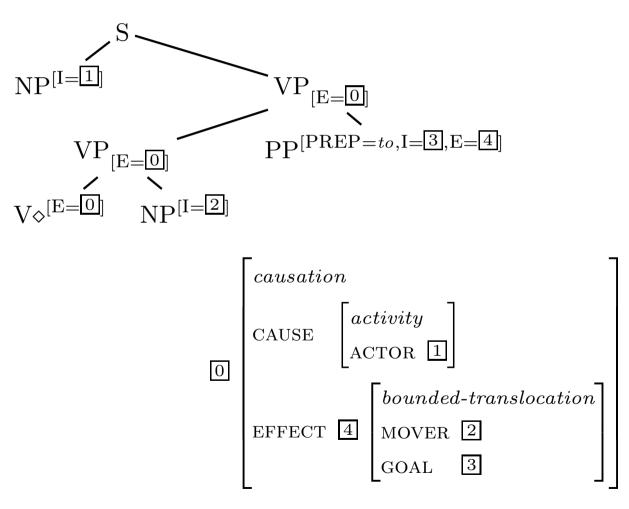
Semantic (de)composition: Dative alternation (1)

DO construction:



Semantic (de)composition: Dative alternation (2)



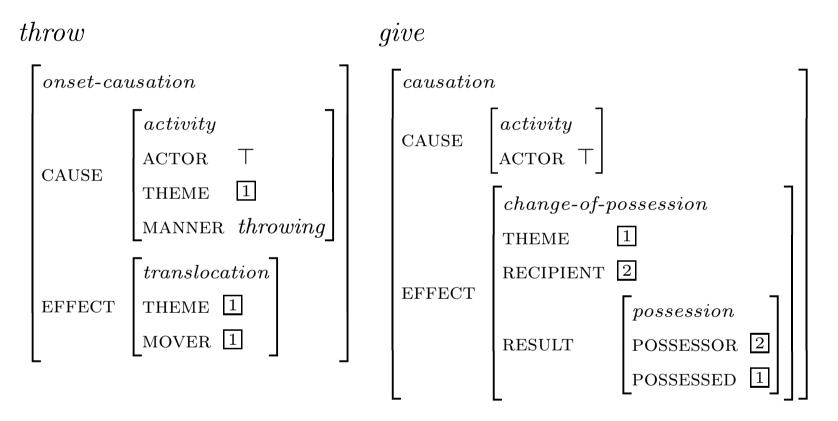


Semantic (de)composition: Dative alternation (3)

Semantic differences between verbs like *give*, *send* and *throw* [Rappaport Hovav and Levin, 2008, Beavers, 2011]:

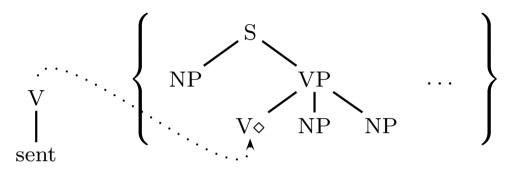
- give: pure caused possession, no implication of motion.
- *hand*: caused possession and motion of the theme to the destination.
- *send*: caused motion towards a destination but not necessarily arrival.
- *throw*: caused motion, existence of destination is not lexicalized.

Semantic (de)composition: Dative alternation (4)



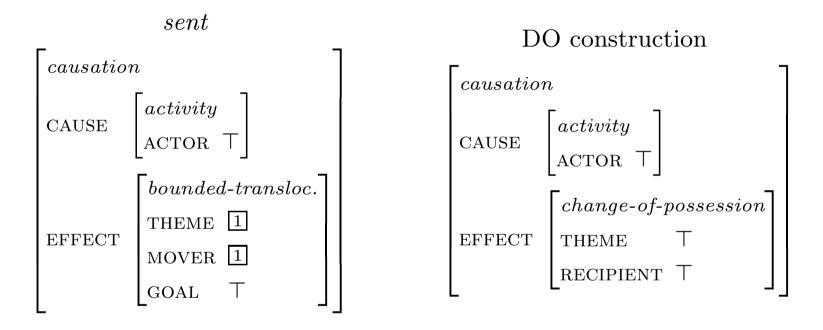
Semantic (de)composition: Dative alternation (5)

Lexical anchoring



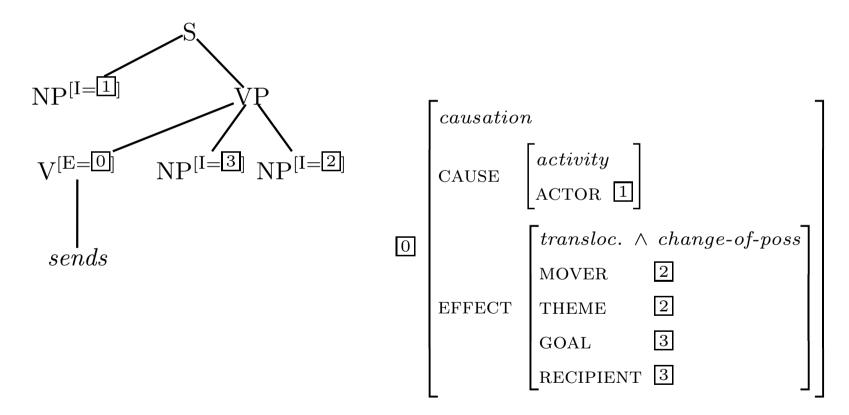
- Because of the unifications of the syntactic s features on the V nodes, the frames of the unanchored tree and of the lexical anchor unify.
- In some cases, the two frames have different types and apparently do not unify.

Semantic (de)composition: Dative alternation (6) Example:



Semantic (de)composition: Dative alternation (7)

But: we allow for multiple types and therefore, unfication is actually possible. Resulting anchored tree:



Semantic (de)composition: Dative alternation (8)

- The effected event can be characterized as a conjunction of the types *bounded-translocation* and *change-of-possession*.
- The appropriate matching of the semantic roles is enforced by additional constraints on the features.
- In the result of the unification, a participant can thus have different semantic roles that reflect the ways in which it is involved in the different characterizations of the event.

Summary

- We aim at giving a detailed analysis of the (de)composition of the meaning of verbs and verb-based constructions.
- LTAG's extended domain of locality allows a straightforward description of constructions as unanchored elementary trees.
- These constructions are combined with the meaning of the verbal head in the process of lexical anchoring.
- We have treated two test cases in order to show how the approach works, directed motion expressions and the dative alternation.

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