Polysemy and Coercion – A Frame-based Approach Using LTAG and Hybrid Logic

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- semantic composition is triggered by syntactic composition,
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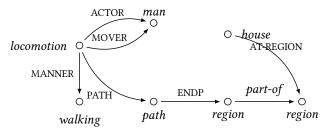
- (1) a. Mary began the book.
 - b. John left the party.
 - c. Mary mastered the heavy book on magic.

We propose to use **frames** as a way to represent rich lexical structures.

- Frames are a representation format of conceptual and lexical knowledge.
- They are commonly presented as semantic graphs with labelled nodes and edges where nodes correspond to entities (individuals, events, ...) and edges to (functional or non-functional) relations between these entities.

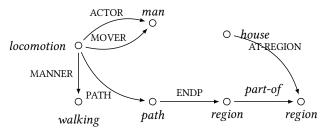
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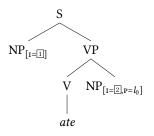


Frames can be formalized as extended typed feature structures.

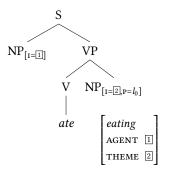
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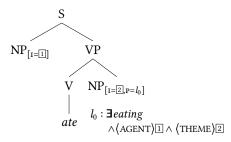
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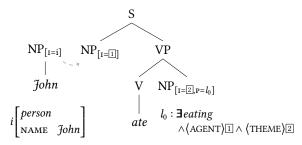
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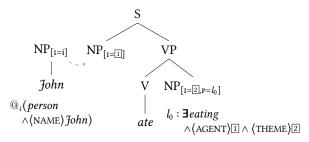
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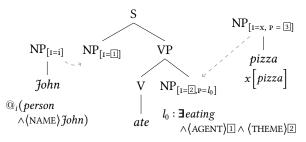
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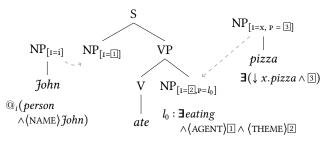
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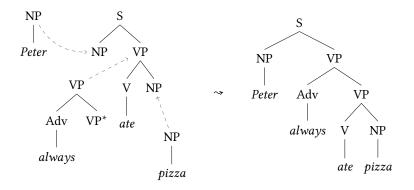
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LTAG and frames

Lexicalized Tree Adjoining Grammar (LTAG, Joshi & Schabes (1997); Abeillé & Rambow (2000)):

- Finite set of **elementary trees**.
- Larger trees are derived via the tree composition operations substitution (replacing a leaf with a new tree) and adjunction (replacing an internal node with a new tree).



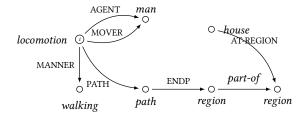
Syntax semantics interface (Kallmeyer & Osswald, 2013; Kallmeyer et al., 2016):

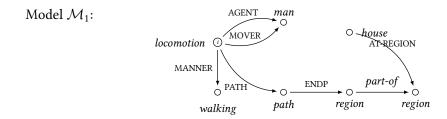
- Link a semantic representation to an entire elementary tree.
- Semantic representations: frames, expressed as typed feature structures, or rather HL formulas that describe frames.
- Interface features relate nodes in the syntactic tree to nodes in the frame graph.
- Model composition by unifications triggered by substitution and adjunction.

Hybrid Logic is an extended version of *modal logic* (Blackburn et al., 2007)

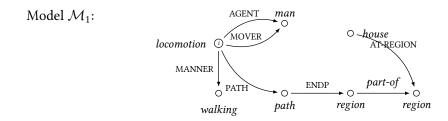
- Modal logic has been proposed as a logic for feature structures (Blackburn, 1993).
- It supports the local perspective on graphs that we adopt when talking about frames: Formulas are evaluated in a specific node.
- Extensions of modal logic allow to incorporate the logical operators we need. This leads to *hybrid logic* (HL, Areces & ten Cate, 2007)

Model \mathcal{M}_1 :





- *region* is true in the two nodes on the right at the bottom.
- (AGENT) *man* is true at the *locomotion* node *i*.
- *locomotion* ∧ (MANNER) *walking* ∧ (PATH)(ENDP) ⊤ is also true at the *locomotion* node *i*.



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HL extends this with

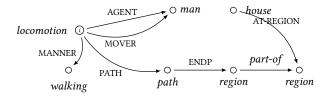
- the possibility to name nodes in order to go back to them without following a specific path;
- quantification over nodes.

Given:

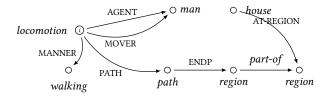
- Rel = Func ∪ PropRel (functional/non-functionsl relational symbols),
- Type (type symbols = propositional variables),
- Nom (nominals = node names), Nvar (node variables), Node := Nom ∪ Nvar.

Forms ::= $\top |p| n |\langle R \rangle \phi | \exists \phi | @_n \phi | \downarrow x.\phi | \exists x.\phi | \neg \phi | \phi_1 \land \phi_2$

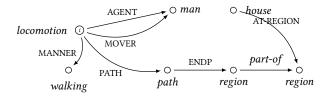
with $p \in \text{Type}$, $n \in \text{Node}$, $R \in \text{Rel}$, ϕ , ϕ_1 , $\phi_2 \in \text{Forms}$.



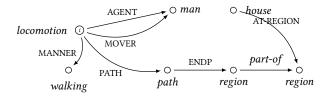
The truth of a formula is defined wrt. a specific node w of a model \mathcal{M} and some assignment mapping Node to the nodes in \mathcal{M} . (For Nvar, this is g.)



J ϕ is true in *w* if there exists a *w'* in \mathcal{M} that makes ϕ true. I.e., we move into some node in our frame and there ϕ is true. **J***house* is true in any node in \mathcal{M}_1 .

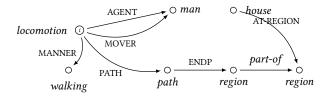


∃φ is true in w if there exists a w' in M that makes φ true.
 I.e., we move into some node in our frame and there φ is true.
 ∃house is true in any node in M₁.
 As usual: ∀φ ≡ ¬∃(¬φ)
 ∀(path → ⟨ENDP⟩T) is true in any node in M₁.



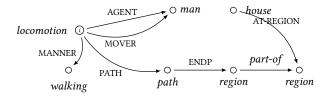
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- Q_nφ is true in w if φ is true in the node assigned to n.
 I.e., we move into the (unique) node named n and there, φ is true.

 $@_i locomotion$ is true in any node in \mathcal{M}_1 .



↓ *x*. φ is true in *w* if φ is true in *w* under the assignment g^x_w.
 I.e., we call the node we are located at *x*, and then φ is true in that node.

 $\langle PATH \rangle \langle ENDP \rangle \langle part-of \rangle \downarrow x.(region \land \exists (house \land \langle AT-REGION \rangle x))$ is true in the *locomotion* node in \mathcal{M}_1 .



■ $\exists x.\phi$ is true in *w* if there is a *w*' such that ϕ is true in *w* under an assignment $g_{w'}^{x}$.

I.e., there is a node that we name x but for the evaluation of $\phi,$ we do not move to that node.

 $\exists x. \langle PATH \rangle \langle ENDP \rangle \langle part-of \rangle (x \land region) \land \exists (house \land \langle AT-REGION \rangle x)$ is true in the *locomotion* node in \mathcal{M}_1 .

- (2) a. The book is heavy.
 - b. The book is interesting.

phys-obj information

book is inherently polysemous between a physical object reading and an information content reading (**dot object**, Pustejovsky, 1998).

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book is inherently polysemous between a physical object reading and an information content reading (**dot object**, Pustejovsky, 1998).

- (3) a. John read the book.
 - b. John read the story.
 - c. John read the blackboard.

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book is inherently polysemous between a physical object reading and an information content reading (**dot object**, Pustejovsky, 1998).

- (3) a. John read the book.
 - b. John read the story.
 - c. John read the blackboard.
 - *read* allows for the direct selection of the dot object *book*, (3-a)
 - It also enables coercion of its complement from the type *information*, (3-b), as well as the type *phys-obj*, (3-c).

Semantics of the dot object *book*:

- General constraints from our frame signature:
 - (4) a. \forall (book \rightarrow info-carrier)
 - b. \forall (*info-carrier* \rightarrow *phys-obj* \land (CONTENT)*information*)
- The lexical entry of *book* only specifies that the word contributes an element of type *book*.

With (4), we infer that the *book* node is also of types *info-carrier* (supertype of *book*) and *phys-obj* (supertype of *info-carrier*), and it has an attribute (CONTENT) with a value of type *information*.

Semantics of *read* (inspired by Pustejovsky, 1998):

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(5) \forall (reading $\rightarrow \exists x. \langle \text{PERC-COMP} \rangle$ (perception $\land \langle \text{ordered-overlap} \rangle x$) $\land \langle \text{MENT-COMP} \rangle$ (comprehension $\land x$))

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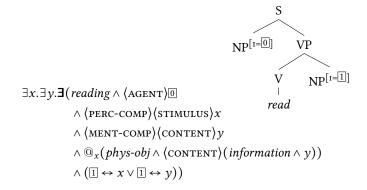
• The *perception* component has an attribute STIMULUS of type *phys-obj*, and the *comprehension* node has an attribute CONTENT which refers to the information that was read. This value is also the CONTENT of the STIMULUS node.

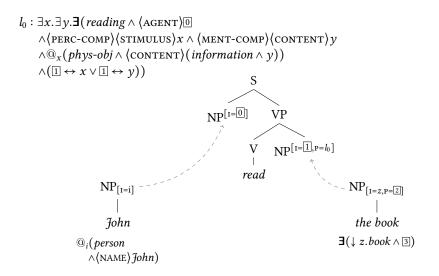
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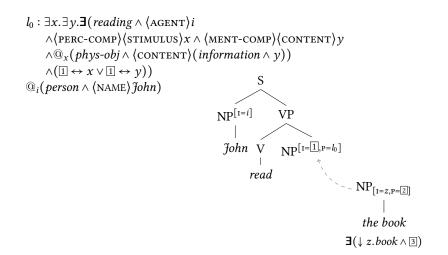
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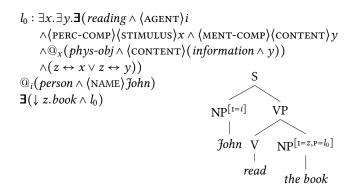
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- The argument of *read* can provide either the stimulus of the perception (*phys-obj*) or its content.







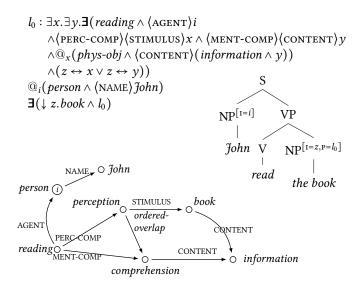


 $l_0: \exists x. \exists y. \exists (reading \land \langle AGENT \rangle i$ \land (perc-comp) (stimulus) $x \land$ (ment-comp) (content) y $\wedge @_x(phys-obj \land (CONTENT)(information \land y))$ $\wedge (z \leftrightarrow x \lor z \leftrightarrow y))$ S $@_i(person \land (NAME) fohn)$ $\exists (\downarrow z.book \land l_0)$ $NP^{[I=i]}$ VP $NP^{[I=z,P=l_0]}$ John

read

the book

 $x \leftrightarrow z$ because of the types



(6) John read the story

We have

(7) a.
$$\forall (story \rightarrow information)$$

b. $\forall (phys-obj \rightarrow \neg information)$

■ Therefore, when combining *story* as a direct object with the above tree-frame pair for *read*, we obtain *y* ↔ *z*.

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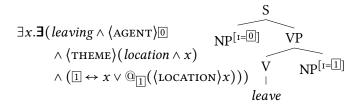
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- Therefore, when combining *story* as a direct object with the above tree-frame pair for *read*, we obtain $y \leftrightarrow z$.
- In addition, from the *reading* frame, we infer that there is a physical object that the story is written on and that John perceives this object while comprehending the story.
- In other words, the physical object is not contributed by the lexical entry of *story* but by coercion, which means in our case by unification and subsequent extension of frames.

(8) John left the party.

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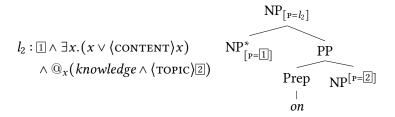
(9) Mary mastered the heavy book on magic.

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$$l_{2}: 1 \land \exists x. (x \lor (\text{content})x) \land @_{x}(knowledge \land (\text{topic})2) \qquad NP_{[P=1]}^{*} \qquad Pp \land Prep \qquad NP^{[P=2]} \land Prep \qquad NP^{$$

(10) \forall (knowledge \rightarrow information $\land \langle \text{TOPIC} \rangle \top$)

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Conclusion

- Frames as semantic representations allow to describe rich semantic structures. The constraints arising from the frame signature can capture various generalizations.
- We use underspecified HL formulas in order to describe frames. HL allows in particular quantification over frame nodes and thereby also over subevents, which is important for characterizing rich event structures.
- This flexible architecture allows to account for polysemy and for different coercion phenomena in a monotonic and compositional way, without assuming any additional operators that are not related to syntactic structure and syntactic operations.

Thank you!

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